Velodyne LiDAR® Puck Hi-Res HIGH RESOLUTION REAL-TIME LIDAR SENSOR

Puck Hi-Res

Velodyne LiDAR's Puck Hi-Res is a higher resolution version of the popular Puck and is used in applications that require increased resolution in the point cloud. The Puck Hi-Res has similar performance to the Puck with the key difference being a higher vertical resolution of 1.33°, with an accompanying 20° vertical field of view. The higher resolution enables detection of objects at longer distances at comparable frame sizes. As a result, the Puck Hi-Res provides more detailed views for applications such as autonomous vehicles, surveillance and 3D mapping/imaging, generating up to ~600,000 points/second.

Like the Puck, the Puck Hi-Res has best-in-class power, which enables operation over a wide temperature range. It's use of off-the-shelf components enables enhanced scalability and attractive volume pricing. Like other Velodyne sensors, the Puck Hi -Res has world-class technical support available across North America, Europe & Asia from the world's leading lidar company.



Security

Mapping

Puck Hi-Res at a glance

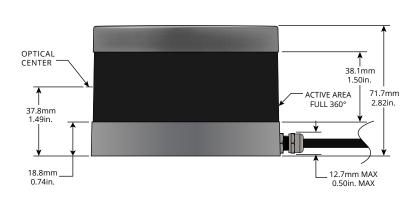
Automotive

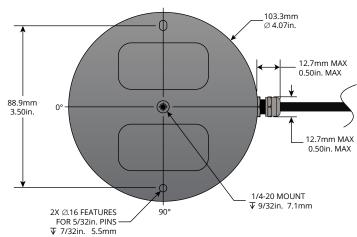
100 m range with compact form factor

Industrial

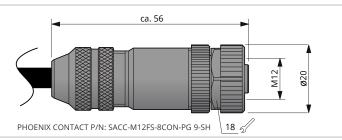
- Higher resolution option in the Puck family
- Proven, Class 1 eye-safe 905 nm technology
- Best-in-class accuracy and calibrated intensity
- Best-in-class power & temperature range
- Sensor-to-sensor interference mitigation feature
- Versatile, with attractive volume pricing

DIMENSIONS (Subject to change)





M12 CONNECTOR OPTION





High Resolution Real-Time Lidar Sensor

The Puck Hi-Res provides high definition 3-dimensional information about the surrounding environment.



	Specifications:
Sensor:	 16 Channels Measurement Range: 100 m Range Accuracy: Up to ±3 cm (Typical)¹ Field of View (Vertical): +10.0° to -10.0° (20°) Angular Resolution (Vertical): 1.33° Field of View (Horizontal): 360° Angular Resolution (Horizontal/Azimuth): 0.1° – 0.4° Rotation Rate: 5 Hz – 20 Hz Integrated Web Server for Easy Monitoring and Configuration
Laser:	 Laser Product Classification: Class 1 Eye-safe per IEC 60825-1:2007 & 2014 Wavelength: 903 nm
Mechanical/ Electrical/ Operational	 Power Consumption: 8 W (Typical)² Operating Voltage: 9 V – 18 V (with Interface Box and Regulated Power Supply) Weight: ~830 g (without Cabling and Interface Box) Dimensions: See diagram on previous page Environmental Protection: IP67 Operating Temperature: -10°C to +60°C³ Storage Temperature: -40°C to +105°C
Output:	 3D Lidar Data Points Generated: Single Return Mode: ~300,000 points per second Dual Return Mode: ~600,000 points per second 100 Mbps Ethernet Connection UDP Packets Contain: Time of Flight Distance Measurement Calibrated Reflectivity Measurement Rotation Angles Synchronized Time Stamps (µs resolution) GPS: \$GPRMC and \$GPGGA NMEA Sentences from GPS Receiver (GPS not included)

63-9318 Rev-F VLP-16-HI-RES

- 1. Typical accuracy refers to ambient wall test performance across most channels and may vary based on factors including but not limited to range, temperature and target reflectivity.
- 2. Operating power may be affected by factors including but not limited to range, reflectivity and environmental conditions.
- 3. Operating temperature may be affected by factors including but not limited to air flow and sun load.





+1.309.291.0966 | AutonomouStuff.com | info@AutonomouStuff.com

