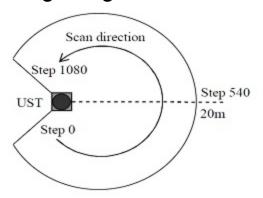


Features

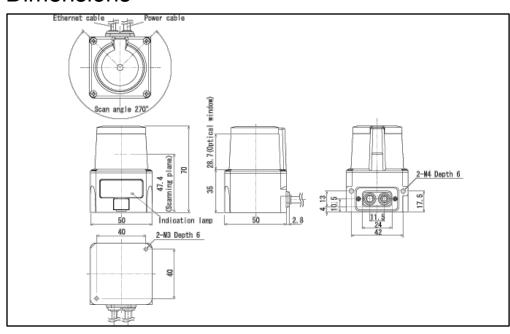
- The smallest and the lightest of its kind, 130g
- Mid-detection range 10m/20m, Wide detection angle 270, Fast response 25msec, High angular resolution 0.25°
- It is possible to detect size, position and the moving direction of objects.

Laser Scanning Image

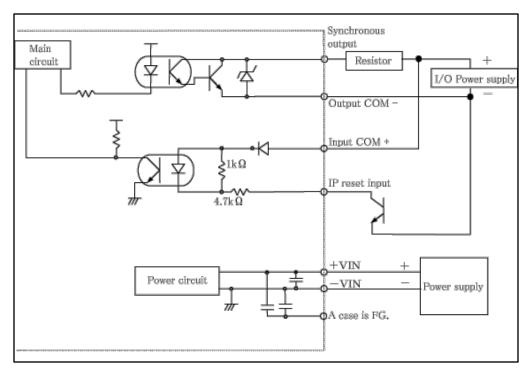


Measurement steps 1081 Detection angle 270° Angular resolution 0.25°

External Dimensions



Output Circuit



Connection

Power source, I/O cable				
Cable length: 1000mm Flying lead cable(AWG28)				
Color	Signal			
Red	COM Input+			
Gray	COM Output-			
Light Blue	IP Reset Input			
Orange	Synchronous Output			
Brown	+VIN(12VDC/24VDC)			
Blue	-VIN			
Note: Direction of Inputs and Outputs are mentioned from the sensor's side.				
Ethernet cable				
Cable length: 300mm				
Color	Signal			
Blue	TX+			
White	TX-			
Orange	RX+			
Yellow	RX-			

Applications

Autonomous robots



Evironmental recognition

Air touch panel



Projecting image linked with hands' motion

People counting



Counting the number of visitors at public facilities for marketing purposes

Unmaned Aerial Vehicle



Small and light enough to mount on UAVs for environmental recognition

Interactive exhibit



Interactive attraction

Analysis of human movement patterns



Adjusting air-conditioning and lighting depending on the density of people for energy saving

Specifications

	Product name	Scanning Laser Range Finder			
	Model	UST-10LX	UST-20LX		
	Supply voltage	DC 12V/DC 24V (operation range 10 to 30V ripple within 10%)			
	Supply current	150mA or less (during start up 450mA is necessary.)			
	Light source	Laser semiconductor (905nm), Laser class 1 (IEC60825-1:2007)			
	Detection range	0.06m to 10m (white Kent sheet) 0.06m to 4m (diffuse reflectance 10%) Max. detection distance : 30m	0.06m to 20m (white Kent sheet) 0.06m to 8m (diffuse reflectance 10%) Max. detection distance : 60m		
	Accuracy	±40mm*1			
	Repeated accuracy	σ<30mm ^{*1}			
	Scan angle	270°			
	Scan speed	25ms (Motor speed 2400rpm)			
	Angular resolution	0.25*			
	Start up time	Within 10 sec (start up time differs if malfunction is detected during start up)			
	Input	IP reset input, photo-coupler input(current 4mA at ON)			
	Output	Synchronous Output, photo coupler open collector output 30VDC 50mA MAX.			
	Interface	Ethernet 100BASE-TX			
	LED display	Power supply LED display(Blue): Blinks during start up and malfunction state.			
	Surrounding intensity	Less than 15,000lx Note : Avoid direct sunlight or other illumination sources as it may cause sensor malfunction			
	Ambient temperature and humidity	-10° C to +50° C, below 85%RH(without dew, frost)			
	Storage temperature and humidity	-30° C to +70° C, below 85%RH(without dew, frost)			
Vibration resistance		10 to 55Hz double amplitude of 1.5mm for 2hrs in each X, Y, and Z direction			
		55 to 200Hz 98m / s $^{\rm 2}$ sweep of 2min for 1hr in each X,Y and Z direction			
	Vibration resistance(Operating)	$55\ to\ 150\mbox{Hz}\ 19.6\mbox{m/s}^2$ sweep of 2min for 30min in each X,Y and Z direction			
	Shock resistance	196m/s ² (20G) X,Y and Z direction 10 times.			
	EMC standards	(EMI) EN61326-1:2013 EN55011:2009 + A1:2010 (EMS) EN61326-1:2013 EN61000-4-2:2009 EN61000-4-3:2006 + A1:2008 + A2:2010 EN61000-4-4:2012 EN61000-4-6:2009 EN61000-4-8:2010			
	Protective structure	IP65			
	Weight	130g(Excluding cable)			
	Material	Front case: Polycarbonate, Rear case: Aluminum			
	Dimensions (W×D×H)	50×50×70mm(sensor only)			
	*1 Under the factory standard testing conditions using white Kent sheet				

^{*1.} Under the factory standard testing conditions using white Kent sheet.



